

	r 1: Design Considerations 1-1 to 1-35	1.10.1	Aesthetics	1
1.1	Introduction to Machine Design1-2	1.10.2	Importance of Aesthetic	
1.2	Design Process (Phases of Design)1-2		Considerations in Design	1
1.3	Design Procedure1-4	1.10.3	Guidelines in Aesthetic Design	1
l.4	Standards and Codes in Design1-5	1.10.4	Aspects of Aesthetic Design	1
.4.1	Advantages of Standardization1-5	1.11	Ergonomic Considerations In Design	.1
		1.11.1	Ergonomics	1
1.4.2	Types (Categories) of Standards1-5 Preferred Series1-6	1.11.2	Areas Covered Under Ergonomics	1
l.5		1.11.3	Communication between Man (User)	
.5.1	Advantages of Preferred Series1-7 Introduction to Tolerances1-8		and Machine	1
.6		1.11.4	Working Environment	1
.6.1	Methods of Making Provisions of Permissible Variations in Dimensions and Geometry1-8	1.11.5	Practical Example of Ergonomics in Design	1
.7	Tolerances (Dimensional Tolerances)1-8	1.11.6	Ergonomics, Aesthetics and Performance	1
7.1	Terminology used in Relation to Tolerances1-9	1.12	Manufacturing Considerations in Design	
.7.2	Types of Tolerances1-10		(Principles to be Followed in Design for	
.7.3	Designation of Tolerances		Manufacture)	.1
	and Grades of Tolerance1-11	1.13	Design Considerations for Castings	.1
.7.4	B. I. S. System of Designation of Tolerances 1-12	1.14	Design Considerations for Forgings	.1
.7.5	Methods of Representation of Dimensional	1.15	Assembly Considerations in Design	
.7.0	Tolerances on Drawings1-13		(Design for Assembly)	.1
.8	Fits1-13	Chapte	er 2: Design of Coupling 2-1 to	2
.8.1	Types of Fits1-13	2.1	Couplings	
.8.2	B.I.S. System of Designation of Fits1-14	2.1.1	Purposes of Using Coupling	
.8.3	Systems of Fits1-14	2.1.1		
.8.4	Conditions for Different Types of Fits1-15		Classification of Couplings Difference (Comparison) between	••••
	7 1	2.1.3		
.8.5	Selection of Fits1-15			
	Selection of Fits 1-15 Allowance 1-15	2.2	Rigid and Flexible Couplings	
.8.6	Allowance1-15	2.2	Rigid and Flexible Couplings	
.8.6	Allowance	2.2.1	Rigid and Flexible Couplings Muff (Sleeve) Coupling Design of Muff Coupling	···
.8.6 .8.7	Allowance	2.2.1 2.2.2	Rigid and Flexible Couplings Muff (Sleeve) Coupling Design of Muff Coupling Summary of Design of Muff Coupling	
.8.6 .8.7	Allowance	2.2.1 2.2.2 2.3	Rigid and Flexible Couplings Muff (Sleeve) Coupling Design of Muff Coupling Summary of Design of Muff Coupling Rigid Flange Coupling	
.8.6 .8.7 . 9	Allowance	2.2.1 2.2.2	Rigid and Flexible Couplings	
.8.6 .8.7 . 9	Allowance	2.2.1 2.2.2 2.3 2.3.1	Rigid and Flexible Couplings	
8.6 8.7 9	Allowance	2.2.1 2.2.2 2.3	Rigid and Flexible Couplings	
.8.6 .8.7 .9	Allowance	2.2.1 2.2.2 2.3 2.3.1 2.3.2	Rigid and Flexible Couplings	
8.6 8.7 9 9.1	Allowance	2.2.1 2.2.2 2.3 2.3.1 2.3.2 2.4	Rigid and Flexible Couplings	
8.6 8.7 9.1 9.2	Allowance	2.2.1 2.2.2 2.3 2.3.1 2.3.2	Rigid and Flexible Couplings	
8.6 8.7 9.1 9.2	Allowance	2.2.1 2.2.2 2.3 2.3.1 2.3.2 2.4 2.4.1	Rigid and Flexible Couplings	
1.8.6 1.8.7 1.9 1.9.1 1.9.2	Allowance	2.2.1 2.2.2 2.3 2.3.1 2.3.2 2.4	Rigid and Flexible Couplings Muff (Sleeve) Coupling Design of Muff Coupling Summary of Design of Muff Coupling Rigid Flange Coupling Design of Protected Type Rigid Flange Coupling Summary of Design of Rigid Flange Coupling Bushed-Pin Type Flexible Flange Coupling Design of Bushed - Pin Type Flexible Flange Coupling Summary of Design of Bushed-Pin Type	
1.8.5 1.8.6 1.8.7 1.9 1.9.1 1.9.2 1.9.3	Allowance	2.2.1 2.2.2 2.3 2.3.1 2.3.2 2.4 2.4.1	Rigid and Flexible Couplings	 2



Chapte	r 3: Design of Springs 3-1 to 3-56	Chapter	4: Pressure Vessels 4-1 to 4-37
3.1	Introduction to Springs3-2	4.1	Types of Cylinders4-2
3.1.1	Functions of Springs3-2	4.2	Thin Cylinders4-2
3.2	Types of Springs3-2	4.2.1	Stresses in Thin Cylinders4-2
3.3	Terminology for Helical	4.2.2	Stresses in Thin Spherical Vessels4-4
	Compression springs3-4	4.3	Thick Cylinders4-7
3.4	Types of Ends for Helical	4.4	Thick Cylinders Subjected to Internal
	Compression Springs3-5		and External Pressures4-7
3.5	Types of Ends for Helical	4.5	Thick Cylinders Subjected to Internal
	Tension Springs3-6		Pressure4-10
3.6	Materials for Helical Springs3-6	4.5.1	Principal Stresses at Inner and Outer Surfaces
3.6.1	Desirable Properties (Characteristics)		of Cylinder Subjected to Internal Pressure4-11
	of Spring Material3-6	4.5.2	Principal Stresses used in Design of Thick
3.6.2	Different Materials used for Helical Springs3-6		Cylinder Subjected to Internal Pressure4-11
3.7	Stresses in Helical Springs3-8	4.6	Design of Thick Cylinders Subjected
3.7.1	Summary of Stresses in Helical Springs3-10		to Internal Pressure4-13
3.8	Deflection of Helical Springs 3-10	4.6.1	Design Based on Maximum Principal Stress
3.9	Design of Helical Compression		Theory (Lame's Equation)4-13
	and Tension Springs 3-11	4.6.2	Design Based on Maximum Principal Strain Theory
3.9.1	Strength Consideration3-11		(Clavarino's Equation and Birnie's Equation)4-14
3.9.2	Stiffness Consideration3-12	4.6.3	Design Based on Maximum Shear Stress
3.9.3	Buckling of Spring3-12	464	Theory4-15
3.9.4	Summary of Design of Helical Compression	4.6.4	Design Based on Distortion Energy Theory4-16
	and Tension Springs3-13	4.7	Thick Cylinders Subjected to External
3.10	Helical Springs in Combination3-28	471	Pressure4-25
3.10.1	Helical Springs in Parallel3-28	4.7.1	Principal Stresses Used in Design of Thick
3.10.2	Helical Springs in Series 3-29	4.8	Cylinder Subjected to External Pressure4-26 Increasing Pressure Capacity
3.11	Concentric Helical Springs 3-30	4.0	(Pre-Stressing) of Thick Cylinders4-27
3.11.1	Types of Concentric Springs3-30	4.8.1	Purpose of Pre-Stressing of Thick Cylinders4-28
3.11.2	Radial Clearance in Concentric Springs3-30	4.9	Methods of Pre-Stressing of Thick Methods of Pre-Stressing of Thick
3.12	Leaf Springs	4.7	Cylinders4-28
	Length of Leaf Spring Leaves	4.9.1	Autofrettage4-28
3.12.1		4.9.2	Wire Wound Cylinders4-29
3.12.2	Strength and Stiffness of Leaf Spring3-42	4.9.3	Tape Wound Cylinders4-29
3.13	Nipping of Leaf Springs3-43	4.9.4	Compound Cylinders4-29
3.13.1	Strength and Stiffness of Leaf	4.10	List of Formulae4-36
2 1 4	Spring with Nipping3-44		
3.14	Surge in Springs	Chapter	5: Rolling Contact Bearings 5-1 to 5-36
3.15	Pre-Stressing of Springs : Shot Peening 3-54	5.1	Introduction to Bearings 5-2
3.16	List of Formulae3-54	5.1.1	Types of Bearings5-2
			Tech Knowledge Publications

5.4	Nomenciature of Rolling Contact Bearing5	Chapte	er 6 : Sliding Contact Bearings	6-1 to 6-48
5.3	Types of Loads on Rolling Contact Bearings 5	-2	<u> </u>	
5.4	Types of Rolling Contact Bearings5	-3 6.1	Introduction to Lubrication	6-2
5.4.1	Ball Bearings5	-3 6.2	Lubricants	6-2
5.4.2	Roller Bearings5	6.2.1	Functions of Lubricants	6-2
5.4.3	Comparison between Ball and Roller Bearings 5	-7 6.3	Physical and Chemical	
5.4.4	Applications of Rolling Contact Bearings5	-8	Properties of Lubricants	6-2
5.5	Designation of Rolling Contact Bearings5	· 8 6.3.1	Viscosity	6-2
5.6	Basic Static Capacity	6.3.2	Viscosity Index	6-6
	(Basic Static Load Rating) of Bearings (C ₀)5	.9 6.3.3	Oiliness	6-6
5.7	Stribeck's Equation for Basic Static	6.3.4	Specific Gravity or Relative Density	
	Capacity of Bearings5		Specific Heat	
5.8	Equivalent Static Load5-1		Flash Point	
5.9	Bearing Life5-1		Fire Point	
5.10	Basic Dynamic Capacity (Basic Dynamic	6.3.8	Pour Point	
	Load Rating) of Bearings (C)5-1		Foaming	
5.11	Equivalent Dynamic Load (P _e) 5-1	6.3.10	Oxidation Stability	
5.12	Load-Life Relationship5-1		Acidity	
5.13	Selection of Bearing Life 5-1	4.	,	
5.14	Selection of Bearing from	6.3.12	Alkalinity	
	Manufacturer's Catalogue5-1	6.3.13	Demulsibility	
5.15	Bearings with Probability of Survival	6.4	Desirable Properties of Lubricant	
	Higher Than 90 Percent 5-2	6.5	Classification of Lubricants	
5.16	Adjusted Life of Bearing5-2	6.6	Lubricating Oils (Liquid Lubricants)	
5.17	Equivalent Dynamic Load for Bearing	6.6.1	Natural Oils (Vegetable and Animal Oils)	
	Under Cyclic Loads 5-2	6.6.2	Mineral Oils	
5.18	Equivalent Dynamic Load for Continuously	6.6.3	Mineral Oils with Additives	
	Variable Cyclic Loads 5-3	6.6.4	Synthetic Oils	6-10
5.19	Taper Roller Bearing 5-3	665	Multi-grade Oils	
5.19.1	Nomenclature of Taper Roller Bearing5-3	6.7	Greases	6-10
5.19.2	Mounting of Taper Roller Bearings5-3	6.7.1	Composition of Greases	6-10
5.20	Lubrication of Rolling Contact Bearings 5-3	673	Use of Greases	6-11
5.20.1	Objectives (Purpose) of Lubrication in Rolling	6.7.3	Types of Greases	6-11
	Contact Bearings5-3	6.8	Solid Lubricants	6-11
5.20.2	Guidelines for Selection of Lubricant5-3		Conditions under Which Solid	
5.20.3	Grease Lubrication5-3	33	Lubricants are Used	6-11
5.20.4	Oil Lubrication5-3	600	Applications of Solid Lubricants	6-11
5.21	Failure of Rolling Contact Bearings 5-3		Selection of Lubricants	6-11
5.21.1	Types (Modes) of Failures of Rolling	6.10	Basic Modes of Lubrication	6-12
	Contact Bearings5-3	6.11	Types of Sliding Contact Bearings	6-13
5.22	List of Formulae5-3		Classification of Sliding Contact Bearings	
			Based on Mode of Lubrication	



6.11.2	Classification of Sliding Contact Bearings Based on	7.4	Spur Gear Terminology	7-6
	Relative Motion between Contacting Surfaces 6-15	7.5	Interference in Involute Gears	7-10
6.12	Petroff's Equation for Hydrodynamic	7.6	Minimum Number of Teeth to Avoid	
	Journal Bearings 6-16		Interference	7-11
6.13	Nomenclature of Hydrodynamic	7.7	Standard Systems of Gear Tooth	7-11
	Journal Bearing6-17	7.8	Effects of Pressure Angle	7-12
6.14	Regimes of Hydrodynamic Lubrication 6-18	7.9	Force Analysis of Spur Gears	7-12
6.15	Reynold's Equation for Hydrodynamic	7.10	Types (Modes) of Gear Tooth Failure	7-14
	Lubrication6-19	7.11	Selection of Gear Materials	7-16
6.15.1	Assumptions in Reynold's Equation6-20	7.11.1	Desirable Properties of Gear Material	7-16
6.15.2	Reynold's Equation for Two-Dimensional Flow . 6-20	7.11.2	Gear Materials	7-16
6.16	Design Considerations in Hydrodynamic	7.12	Beam Strength of Spur Gear Tooth	7-19
	Journal Bearings 6-22	7.12.1	Assumptions in Analysis of Beam Strengtl	
6.17	Relations of Variables For Hydrodynamic Journal	7.12.2	Lewis Equation for Beam Strength of	
	Bearings (Raimondi and Boyd Method) 6-23		Spur Gear Tooth	7-19
6.17.1	Design and Performance Variables6-23	7.12.3	Lewis Form Factor (Y)	7-20
6.17.2	Dimensionless Parameters 6-24	7.12.4	Bending Endurance Strength ($\sigma_{\rm h}$)	7-21
6.18	Temperature Rise (Thermal Considerations)	7.12.5	Face Width (b)	
	in Hydrodynamic Journal Bearings	7.12.6	Weaker of Gear and Pinion	
	With Feed Lubrication 6-26	7.13	Wear Strength of Spur Gear Tooth	
6.18.1	Total flow of Lubricating oil (Q)6-26	7.13.1	Load-Stress actor (K)	
6.18.2	Rate of Heat Generation (H _g)6-26	7.13.1	Ratio Factor (Q)	
6.18.3	Rate of Heat Dissipation (H_d)6-26	7.13.2 7.14	Effective Load on Spur Gear Tooth	
6.18.4	Temperature Rise (ΔT)6-27	7.14 7.14.1	Theoretical Tangential Force (F _t)	
6.18.5	Viscosity of Lubricating Oil (μ)6-27	7.14.2	Maximum Tangential Force (F _{max})	
6.18.6	Average Temperature of Lubricating Oil (T_{av}) 6-27			
6.19	Temperature Rise in Self-Contained or	7.14.3	Dynamic Load on Gear Tooth and its Caus	
	Self-Cooled Hydrodynamic	7.14.4	IS Gear Grades	7-25
	Journal Bearings 6-27	7.14.5	Methods of Estimation of Dynamic	7.05
6.20	Selection of Bearing Design Variables for		Load and Effective Load	
	Hydrodynamic Journal Bearings 6-29	7.15	Safety of Gear Pair	
6.21	Design Procedure for Hydrodynamic	7.16	Objectives in Design of Gear Pair	
	Journal Bearings 6-30	7.17	Design of Spur Gear Pair	7-28
6.22	Bearing Materials 6-44	7.18	Power Transmitting Capacity of Spur	
6.22.1	Desirable Properties of Bearing Materials6-44		Gear Pair	_
6.22.2	Materials for Bearings6-45	7.19	List of Formulae	7-53
6.23	List of Formulae6-47	Chapte	r 8 : Helical Gears	8-1 to 8-31
Chapter	7: Spur Gears 7-1 to 7-54	8.1	Introduction	
		8.2	Advantages and Limitations of Helical	Gears 8-2
7.1	Introduction7-2			
7.1 7.2		8.3	Helical Gear Terminology	8-2
	Classification of Gears	8.3 8.4	Helical Gear Terminology Equivalent Spur Gear and Virtual (Formative) Number of Teeth	

8.5	Minimum Number of Teeth on Helical Pinion8-8	Chapte	r 10 : Worm Gears 10-1 to 10-32
8.6	Force Analysis of Helical Gears8-8	10.1	Introduction10-2
8.7	Beam Strength of Helical Gear Tooth8-11	10.2	Advantages and Limitations of Worm
8.7.1	Lewis Form Factor Based on Virtual		Gear Drives10-2
0.7.1	Number of Teeth (Y')8-12	10.3	Terminology of Worm and Worm Gears10-2
8.7.2	Bending Endurance Strength8-12	10.4	Designation of Worm and Worm Gear Pair10-7
8.7.3	Face Width8-12	10.5	Force Analysis of Worm and Worm
	Weaker of Gear and Pinion8-12		Gear Pair10-10
8.7.4		10.5.1	Components of Force Acting on Worm10-10
8.8	Wear Strength of Helical Gear Tooth8-12	10.5.2	Components of Force Acting on Worm Gear10-11
8.9 8.9.1	Effective Load on Helical Gear Tooth8-13 Theoretical Tangential Force (F _t)8-13	10.5.3	Direction of Components of Forces on
			Worm and Worm Gear10-12
8.9.2	Maximum Tangential Force (F _{tmax})8-14	10.6	Sliding (Rubbing) Velocity in Worm
8.9.3	Methods of Estimation of Dynamic Load and Effective Load8-14		and Worm Gear Pair10-12
8.10	Safety of Helical Gear Pair8-16	10.7	Efficiency of Worm and Worm Gear Pair 10-13
8.11	List of Formulae8-30	10.7.1	Factors Affecting Efficiency of Worm
0.11	List of Formulae		Gear Pair10-13
Chapter	9: Bevel Gears 9-1 to 9-30	10.7.2	Self-Locking Worm Gear Pair10-14
9.1	Introduction9-2	10.8	Types (Modes) of Failures in Worm
9.2	Terminology of Bevel Gears9-2		Gear Pair10-15
9.3	Formative Number of Teeth	10.9	Worm and Worm Gear Materials10-15
	(Tredgold's Proximation)9-7	10.9.1	Materials for Worm10-15
9.4	Minimum Number of Teeth on Bevel Pinion9-7	10.9.2	Materials for Worm Gears10-16
9.5	Force Analysis of Straight Bevel Gears9-8	10.9.3	Why Dissimilar Materials for Worm
9.6	Types (Modes) of Bevel Gear Tooth Failure 9-10		and Worm Wheel?10-17
9.7	Materials for Bevel Gears 9-10	10.10	Design of Worm Gear Drive10-17
9.8	Beam Strength of Straight Bevel Gear Tooth . 9-11	10.10.1	Why Worm Gear Always Governs the Design?10-17
9.8.1	Lewis Form Factor Based on Virtual	10.11	Beam Strength of Worm Gear Tooth10-17
	Number of Teeth (Y')9-12	10.11.1	Lewis Form Factor10-18
9.8.2	Permissible Bending Stress9-13	10.11.2	Permissible Bending Stress10-18
9.8.3	Face Width9-13	10.11.3	Face Width10-18
9.8.4	Weaker of Gear and Pinion9-13	10.12	Wear Strength of Worm Gear Tooth10-18
9.9	Wear Strength of Straight Bevel Gear Tooth 9-13	10.13	Effective Load on Worm Gear Tooth10-18
9.9.1	Load-Stress Factor (K)9-14	10.14	Safety of Worm Gear Pair10-19
9.10	Effective Load on Straight Bevel Gear Tooth 9-14	10.15	Thermal Considerations in Worm
9.10.1	Theoretical Tangential Force (F _t)9-14		Gear Drive10-19
9.10.2	Maximum Tangential Force (F _{max})9-15	10.16	Arrangements of Worm Gear Reducer10-29
9.10.3	Methods of Estimation of Dynamic Load and	10.17	List of Formulae10-31
	Effective Load on Straight Bevel Gear Tooth 9-15	Chapte	r 11 : Speed Gear Box 11-1 to 11-46
9.11	Safety of Bevel Gear Pair9-17	11.1	Need of Multi-Speed Gear Box in
9.12	List of Formulae9-28		Machine Tools11-2





11.2	Basic Considerations in Design of	11.14	List of Formulae	11-45
	Multi-Speed Gear Box11-2	Chapte	r 12: Design of Mechanisms	12-1 to 12-63
11.3	Laws of Stepped Regulation of Speeds in	12.1	Introduction	12-2
	Multi-Speed Gear Box11-3	12.2	Valve Gear Mechanism	
11.3.1	Comparison of Laws of Stepped Regulation	12.2.1	Valve	
	of Speeds in Multi-Speed Gear Box11-5	12.2.2	Valve Spring	
11.4	Advantages of Geometric Progression11-6	12.2.2	Rocker Arm	
11.5	Selection of Geometric Progression Ratio	12.2.3	Tappet	
	in Multi-Speed Gear Box11-7	12.2.4	Push Rod	
11.5.1	Geometric Progression Ratio11-8		Cam and Follower	
11.5.2	Effect of Geometric Progression Ratio11-8	12.2.6		12-15
11.5.3	Standard Values of Geometric	12.3	Classification of Material Handling Equipment	12-20
	Progression Ratio (\$\phi\$)11-8	12.3.1	Hoisting Equipment	
11.6	Parameters in Kinematic Design of	12.3.1	Conveyors (Conveying Equipment)	
	Multi-Speed Gear Box11-9	12.3.2	Surface and Overhead Equipment	
11.7	Kinematic Diagram (Gearing Diagram)		• •	
11.0	of Gear Box11-11 Structural Formulae11-11	12.4	Components of EOT Crane	
11.8		12.5	Crane Hook Assembly with Pulleys	
11.8.1	Illustrative Example of Structural Formulae11-12	12.5.1	Crane Hook	
11.8.2	Transmission Range of a Stage (Transmission Group)11-13	12.5.2	Thrust Bearing for Hook	
11.9	Structure Diagrams11-13	12.5.3	Nut for Hook	
11.9.1	Procedure for Constructing Structure	12.5.4	Cross-Piece for Hook	
11.7.1	Diagram11-13	12.5.5	Pulley Axle (Cross-Piece for Pulleys)	
11.9.2	Examples of Structure Diagram11-14	12.5.6	Pulley Bearings	
11.9.3	Features of Structure Diagrams11-14	12.5.7	Shackle Plates	
11.9.4	Types of Structure Diagrams11-15	12.6	Pulley System	
11.9.5	Selection of Optimum Structure Diagram11-15	12.7	Wire Ropes	
11.10	Speed Diagrams and Ray Diagrams11-17	12.7.1	Construction of Wire Rope	
	Procedure for Constructing Speed Diagrams11-17	12.7.2	Designation of Wire Rope	
11.10.1	Features of Speed Diagrams11-17	12.7.3	Applications of Wire Rope	
11.10.2	Selection of Optimum Speed Diagrams11-18	12.7.4	Lay of Wire Ropes	
	Comparison between Structure	12.7.5	Data for Wire Ropes	
11.10.4	Diagram and Speed Diagrams11-18	12.7.6	Modes of Failures of Wire Rope	
11.11	General Guidelines in Developing Kinematic	12.7.7	Static Failure Due to Tensile Stress	
11.11	Diagram (Gearing Diagram) for	12.7.8	Fatigue Failure Due to Bearing Pressur	e12-51
	Multi-Speed Gear Box11-19	12.7.9	Factor of Safety for Wire Ropes	12-52
11.12	Procedure for Kinematic Design of	12.7.10	Summary of Stresses in Wire Ropes	12-52
	Multi-Speed Gear Box for Machine Tools11-21	12.7.11	Selection of Wire Ropes	12-53
11.13	Deviation Diagram for Multi-Speed	12.8	List of Formulae	12-59
	Gear Box11-23			